

FAULT-TOLERANT COMPUTATION IN SEMIGROUPS AND SEMIRINGS

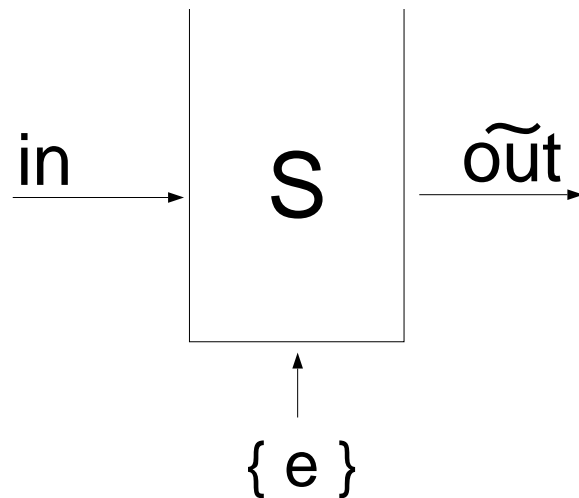
Master of Engineering Thesis
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May 1995

Plan

- Introduction and Definitions
- Fault Tolerance for Semigroup-Based Computations
- Extensions and Future Possibilities
- Contribution

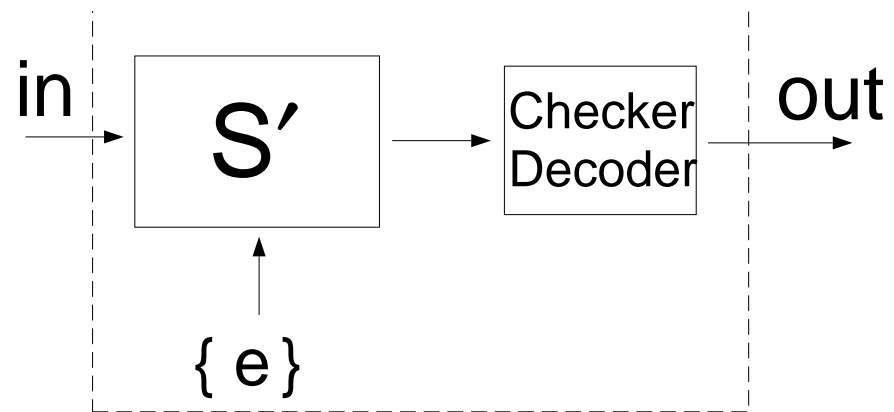
Fault-Tolerant Computational Systems

Unprotected



$$\tilde{\text{out}} = f(\text{in}, \{e\})$$

Protected



Arithmetic Codes \longleftrightarrow ABFT

(... Diamond, 1955 \longleftrightarrow Abraham, 1984 ...)

$n \times n$ Matrix Multiplication

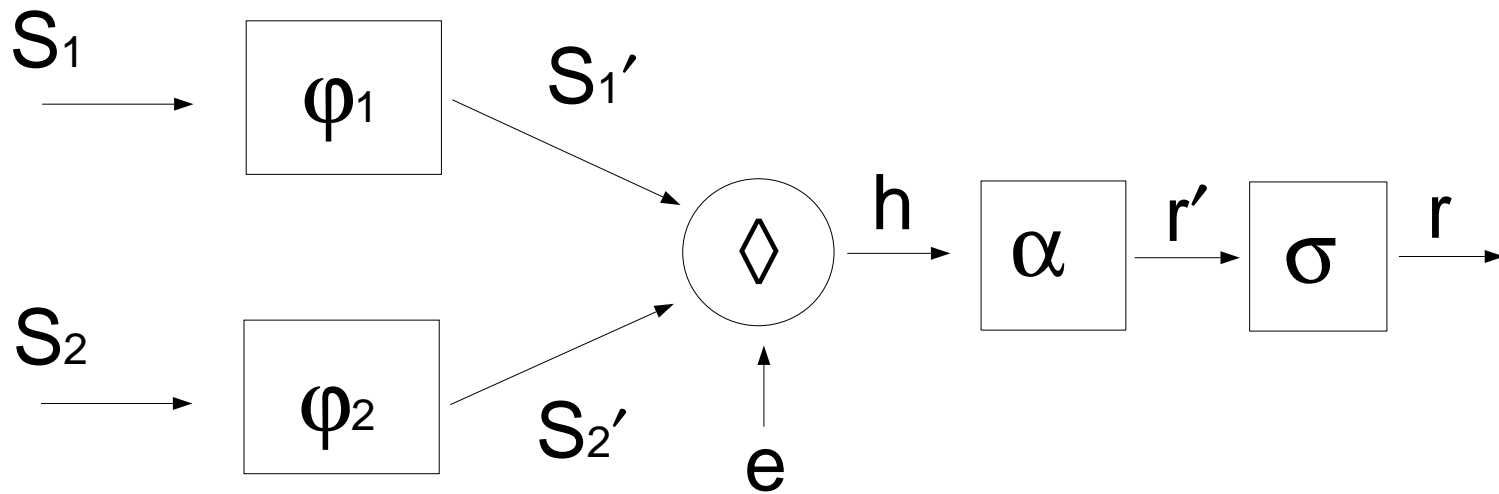
(Abraham et al., 1984 onwards)

$$\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{bmatrix} \times \begin{bmatrix} b_{11} & b_{12} & \dots & b_{1n} \\ b_{21} & b_{22} & \dots & b_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ b_{n1} & b_{n2} & \dots & b_{nn} \end{bmatrix} = \begin{bmatrix} c_{11} & c_{12} & \dots & c_{1n} \\ c_{21} & c_{22} & \dots & c_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ c_{n1} & c_{n2} & \dots & c_{nn} \end{bmatrix}$$

$$\begin{bmatrix} & & A & & \\ c_1 & c_2 & \dots & c_n & \end{bmatrix} \times \begin{bmatrix} B & r_1 \\ & r_2 \\ & \vdots \\ & r_n \end{bmatrix} = \begin{bmatrix} & & C & & r_{S1} \\ & & & & r_{S2} \\ & & & & \vdots \\ c_{S1} & c_{S2} & \dots & c_{Sn} & r_{Sn} \\ & & & & ? \end{bmatrix}$$

Model for Fault-Tolerant Group/Semigroup Computation

(Group Case by Beckmann, MIT, PhD, 1992)



Encoding
Stage

Redundant
Computation

Correction
and
Decoding

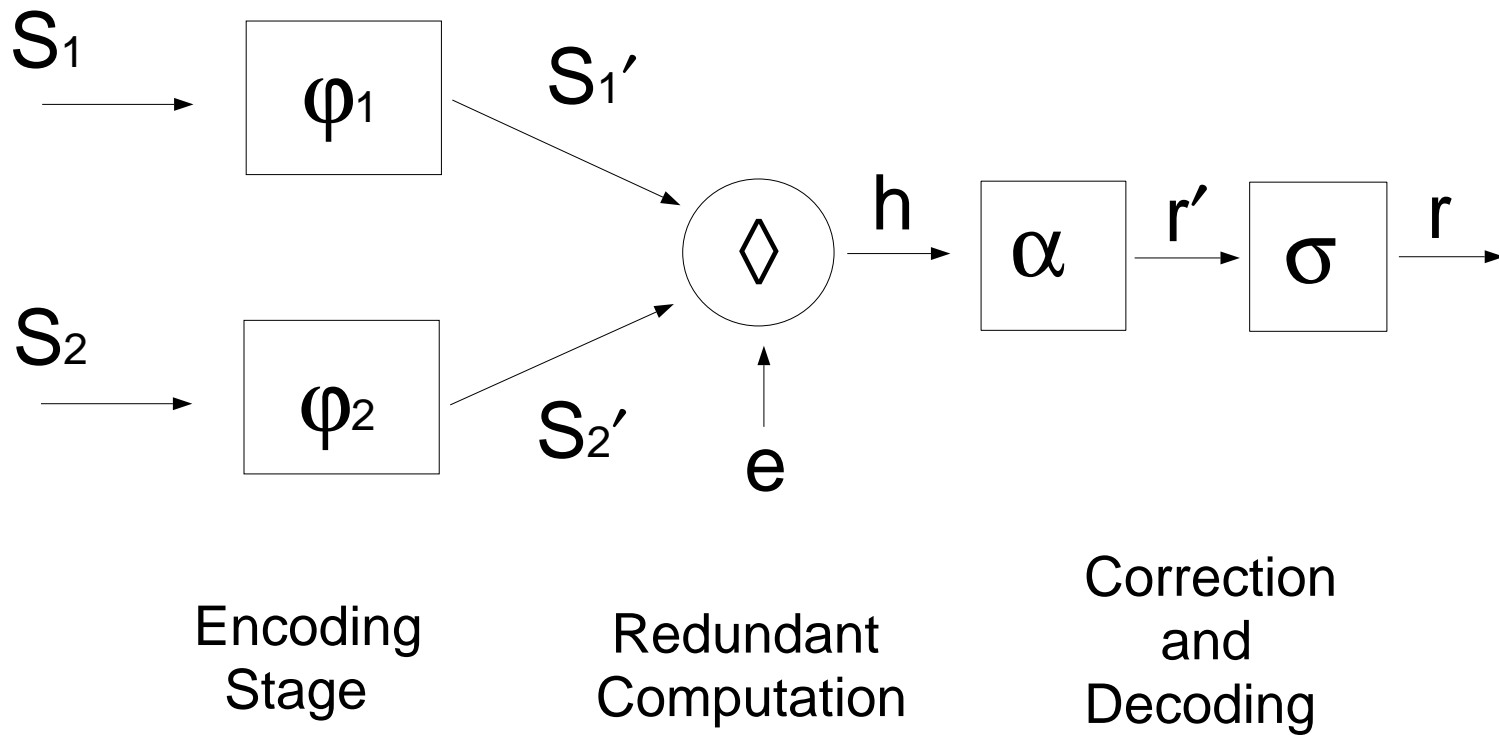
Definition of a Semigroup

Definition: A semigroup $\mathcal{S} = (S, \circ)$ is a set of elements S , and a binary operation \circ , called the *semigroup product*, such that:

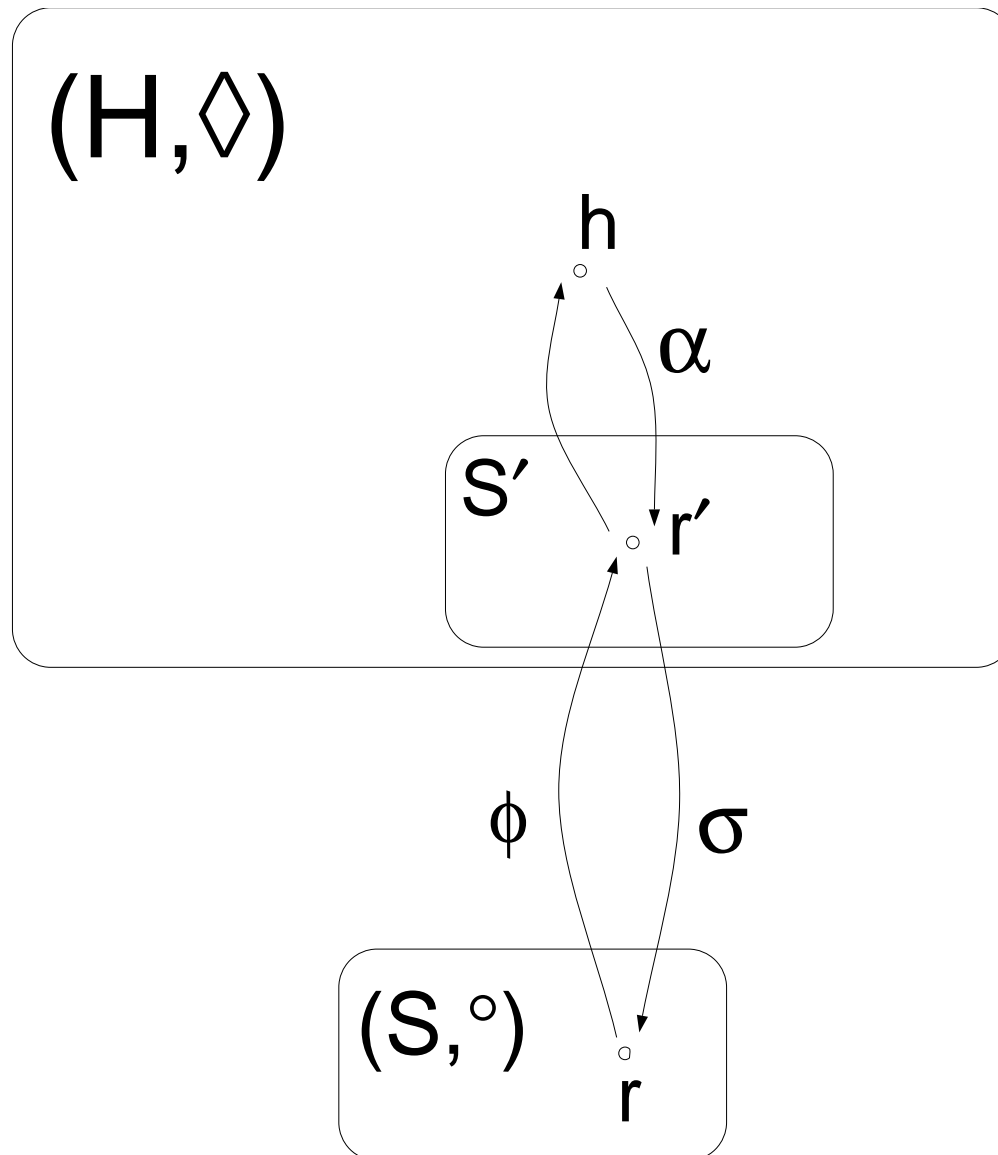
1. For all $s_1, s_2 \in S$, $s_1 \circ s_2 \in S$
2. For all $s_1, s_2, s_3 \in S$, $(s_1 \circ s_2) \circ s_3 = s_1 \circ (s_2 \circ s_3)$

Examples: (\mathbb{Z}, \times) , (\mathbb{N}, \times) , $(\mathbb{N}_0, +)$

Abelian Semigroup Computation



Use of Abelian Semigroup Homomorphisms



Separate Codes

Use a separate channel (known as “parity” channel):

$$\begin{aligned} s_1 &\xrightarrow{\phi} (s_1, t_1) \\ s_2 &\xrightarrow{\phi} (s_2, t_2) \\ s_1 \circ s_2 &\xrightarrow{\phi} (s_1 \circ s_2, t_1 \odot t_2) = (s_1, t_1) \diamond (s_2, t_2) \end{aligned}$$

Parity encoding mapping θ

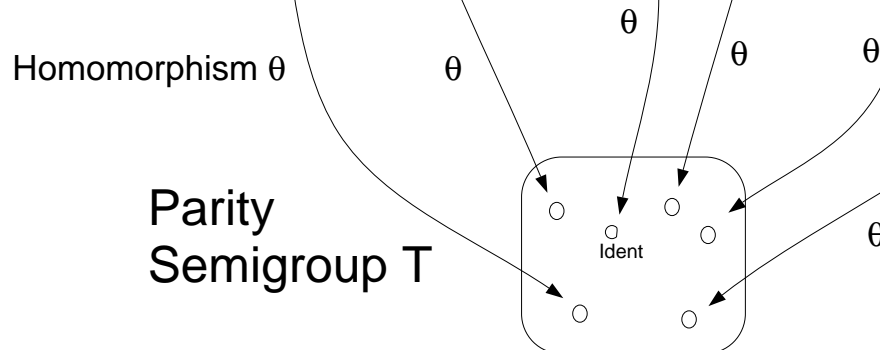
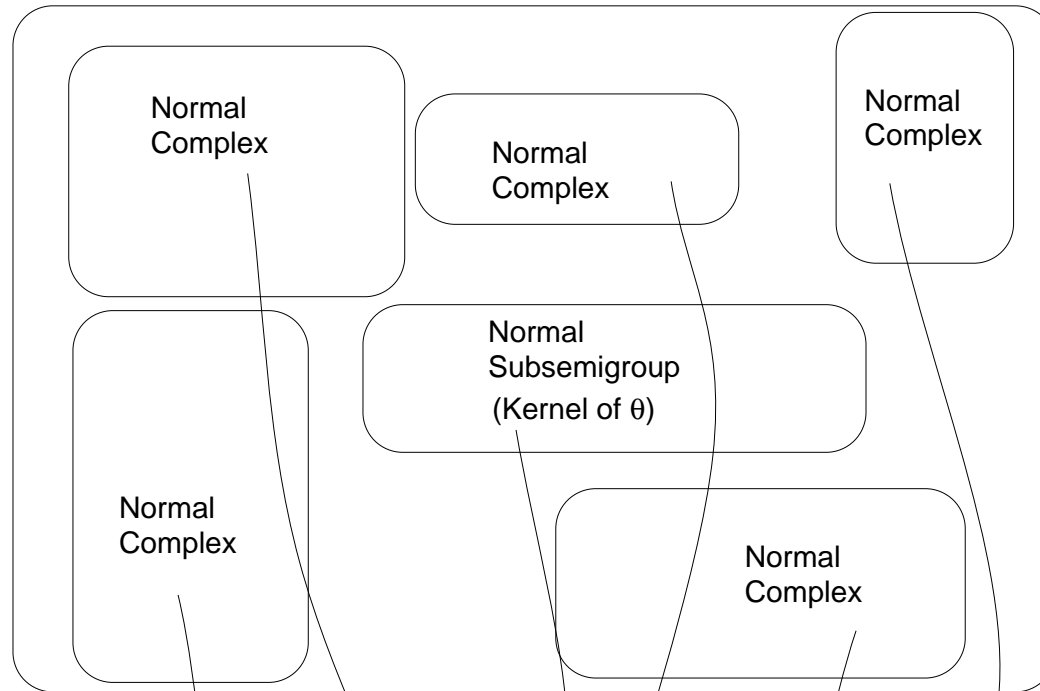
$$t_1 = \theta(s_1)$$

$$t_2 = \theta(s_2)$$

θ is a semigroup homomorphism.

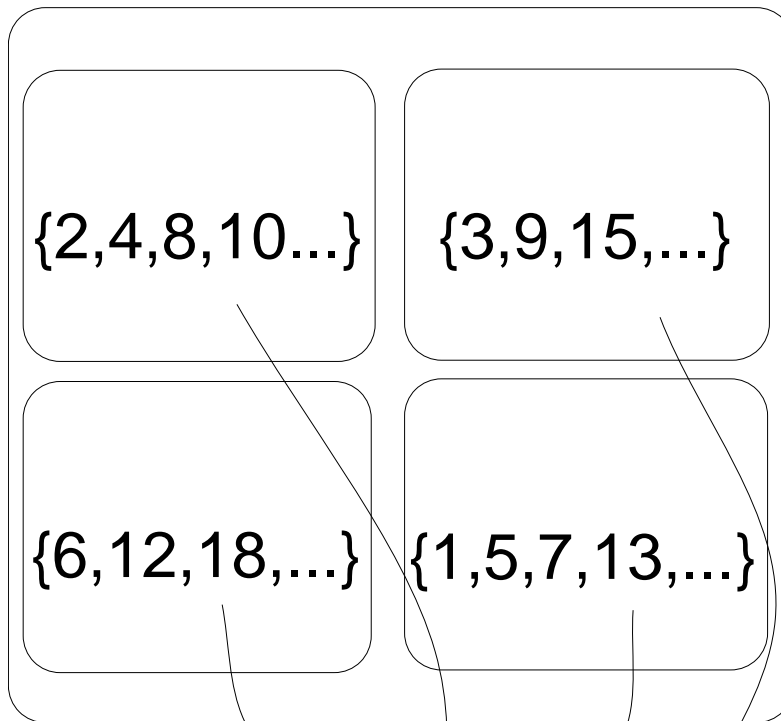
Separate Codes in Semigroups

Original
Semigroup S

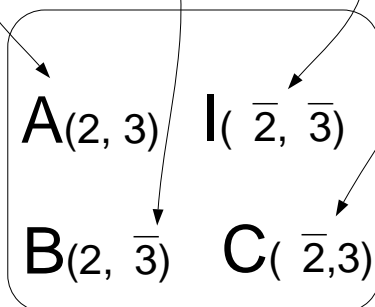


Separate Codes for (N, \times)

Semigroup (N, \times)



Parity
Semigroup



\odot	I	A	B	C
I	I	A	B	C
A	A	A	A	A
B	B	A	B	A
C	C	A	A	C

Extensions and Future Work

- More complicated algebraic structures can be studied. (Already done for semiring computations, such as $(N_0, +, \times)$, and $(Z, max, +)$)
- Future Research
 - 1) Reflect hardware failure modes
 - 2) Study of error correction procedures (including distance metrics, syndromes, etc.)
 - 3) Protect strings of computations.
 - 4) Links to error-correcting coding and automata theory.

Contribution

- Algebraic framework for fault-tolerant semigroup computations
- Separate codes are completely characterized
- Explored various examples